

- Momento angular orbital $\vec{L}$

- Regresamos a $\vec{L}$.

- Describiremos en $\{|\vec{r}\rangle\}$

- Encontraremos que en L^2 son $\hbar^2 l(l+1)$ para l enteros

- Usando que en $\{|\vec{r}\rangle\}$ $\vec{R}$ es $\vec{r}$ y $\vec{P}$ es $-i\hbar\nabla$

$$\vec{L} = \vec{R} \times \vec{P}$$

$$L_x = \frac{\hbar}{i} \left(y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y} \right)$$

$$L_y = \frac{\hbar}{i} \left(z \frac{\partial}{\partial x} - x \frac{\partial}{\partial z} \right)$$

$$L_z = \frac{\hbar}{i} \left(x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right)$$

Usando coordenadas esféricas

$$\int_V r = r^2 \sin\theta dr d\theta d\varphi$$

$$= r^2 dr d\Omega$$

$$d\Omega = \sin\theta d\theta d\varphi$$

$$L_x = i\hbar \left(\sin\varphi \frac{\partial}{\partial\theta} + \frac{\cos\varphi}{\tan\theta} \frac{\partial}{\partial\varphi} \right)$$

$$L_y = i\hbar \left(-\cos\varphi \frac{\partial}{\partial\theta} + \frac{\sin\varphi}{\tan\theta} \frac{\partial}{\partial\varphi} \right)$$

$$L_z = \frac{\hbar}{i} \frac{\partial}{\partial\varphi}$$

which yield:

$$L^2 = -\hbar^2 \left(\frac{\partial^2}{\partial\theta^2} + \frac{1}{\tan\theta} \frac{\partial}{\partial\theta} + \frac{1}{\sin^2\theta} \frac{\partial^2}{\partial\varphi^2} \right)$$

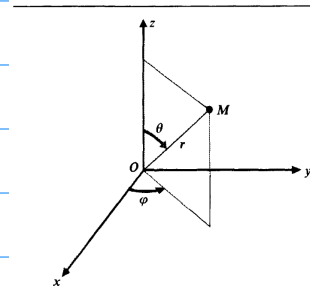
$$L_+ = \hbar e^{i\varphi} \left(\frac{\partial}{\partial\theta} + i \cot\theta \frac{\partial}{\partial\varphi} \right)$$

$$L_- = \hbar e^{-i\varphi} \left(-\frac{\partial}{\partial\theta} + i \cot\theta \frac{\partial}{\partial\varphi} \right)$$

$$\begin{cases} x = r \sin\theta \cos\varphi \\ y = r \sin\theta \sin\varphi \\ z = r \cos\theta \end{cases}$$

with:

$$\begin{cases} r \geq 0 \\ 0 \leq \theta \leq \pi \\ 0 \leq \varphi < 2\pi \end{cases}$$



- Para un $|\psi\rangle$ arbitrario las ecs de ev

$$L^2 |\psi\rangle = \hbar^2 l(l+1) |\psi\rangle$$

$$L_z |\psi\rangle = \hbar m |\psi\rangle$$

toman la forma

$$\langle \vec{r} | L^2 | \psi \rangle = \hbar^2 l(l+1) \langle \vec{r} | \psi \rangle = \hbar^2 l(l+1) \psi(\vec{r})$$

$$\langle \vec{r} | L_z | \psi \rangle = \hbar m \psi(\vec{r})$$

$$\Rightarrow \begin{cases} - \left\{ \frac{\partial^2}{\partial \theta^2} + \frac{1}{\tan \theta} \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} \right\} \psi(r, \theta, \varphi) = l(l+1) \psi(r, \theta, \varphi) & \text{(D-7-a)} \\ - i \frac{\partial}{\partial \varphi} \psi(r, \theta, \varphi) = m \psi(r, \theta, \varphi) & \text{(D-7-b)} \end{cases}$$

- Observaciones:

- Resultados de sección anterior aplican:
para l fijo $m = -l, \dots, l$

- r no aparece; sólo importan θ y φ .

↳ Podemos usar separación de variables $\psi(r, \theta, \varphi) = f(r) Y_l^m(\theta, \varphi)$

- Denotamos a las e.f. $Y_l^m(\theta, \varphi)$

$$L^2 Y_l^m = l(l+1) \hbar^2 Y_l^m$$

$$L_z Y_l^m = \hbar m Y_l^m$$

- Valores para l y m

separación de variables
 $Y_l^m = F(\theta) G(\varphi)$

$$\frac{1}{i} \frac{\partial}{\partial \varphi} Y_l^m = m Y_l^m \Rightarrow Y_l^m = F_l^m(\theta) e^{im\varphi}$$

$$\text{Como } Y_l^m(\theta, \varphi) = Y_l^m(\theta, \varphi + 2\pi)$$

$$e^{im\varphi} = e^{im(\varphi + 2\pi)} \Rightarrow e^{2im\pi} = 1$$

$\Rightarrow m$ es entero

$\Rightarrow l$ es entero.

Sabemos de la teoría general que

$$L_+ Y_l^{m=l} = 0$$

$$\left(\frac{d}{d\theta} - l \cot \theta \right) F_l^l(\theta) = 0 \Rightarrow \frac{dF_l^l(\theta)}{d\theta} = l \frac{\cos \theta}{\sin \theta} F_l^l(\theta)$$

$$\Rightarrow \frac{1}{F_l^l} \frac{d}{d\theta} F_l^l = l \frac{\cos \theta}{\sin \theta} \text{ es } \frac{f'(\theta)}{f(\theta)}$$

$$\Rightarrow \ln F_l^l(\theta) = l \ln(\sin \theta)$$

$$\Rightarrow F_l^l(\theta) = \sin^l(\theta)$$

$$\therefore Y_l^l(\theta, \varphi) = N \sin^l(\theta) e^{il\varphi}$$

Aplicando L_- obtenemos las otras

$$\int_0^{2\pi} \int_0^\pi |Y_l^m(\theta, \varphi)|^2 \sin \theta d\theta d\varphi = 1$$

$l = 0$	$l = 1$	$l = 2$
$Y_0^0 = \sqrt{\frac{1}{4\pi}}$	$Y_1^{\pm 1} = \pm \sqrt{\frac{3}{8\pi}} \sin \theta e^{\pm i\varphi}$ $Y_1^0 = \sqrt{\frac{3}{4\pi}} \cos \theta$	$Y_2^{\pm 2} = \sqrt{\frac{15}{32\pi}} \sin^2 \theta e^{\pm 2i\varphi}$ $Y_2^{\pm 1} = \mp \sqrt{\frac{15}{8\pi}} \sin \theta \cos \theta e^{\pm i\varphi}$ $Y_2^0 = \sqrt{\frac{5}{16\pi}} (3 \cos^2 \theta - 1)$

La expresión general para cualquier valor de l y m está dada por

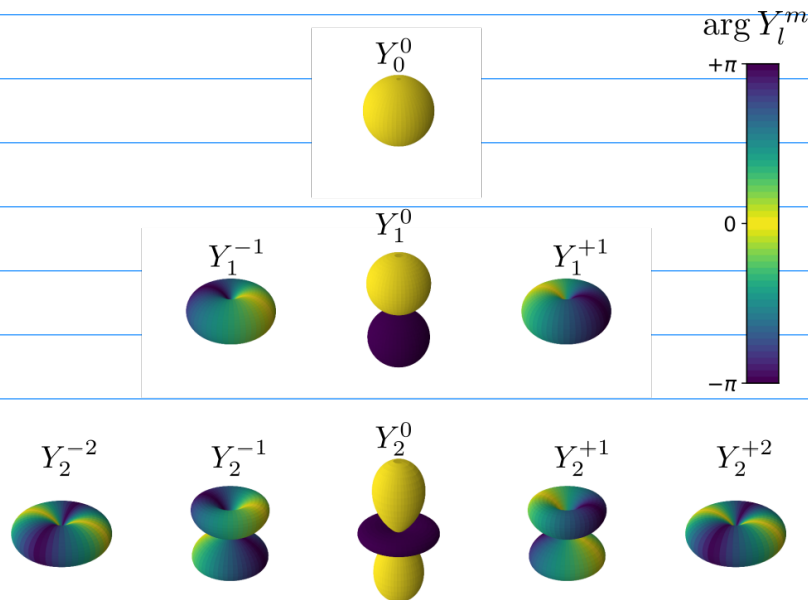
$$Y_l^m(\theta, \varphi) = (-1)^m \sqrt{\frac{(2l+1)(l-m)!}{4\pi(l+m)!}} P_l^m(\cos \theta) e^{im\varphi}, \quad m \geq 0;$$

$$Y_l^{-m}(\theta, \varphi) = (-1)^m Y_l^m(\theta, \varphi)^*;$$

$$P_l^m(x) = (1-x^2)^{|m|/2} \frac{d^{|m|}}{dx^{|m|}} P_l(x);$$

$$P_l(x) = \frac{1}{2^l l!} \frac{d^l}{dx^l} (x^2 - 1)^l.$$

Aquí, a $P_l^m(x)$ se le conoce como polinomio asociado de Legendre.



Los resultados de L_+ , L_- , L^2 , L_z
aplican para Y_l^m